

# HW #8, due Thursday December 4, 2007 at 11:30AM

1. (25 pts) For each of the following four transfer functions, answer the following questions with coherent reasons and without using MATLAB to plot the root-loci:
  - a. Is the transfer function stable?
  - b. What is the relative degree?
  - c. Is the transfer function minimum phase?
  - d. What are the real branches of the root-locus plot?
  - e. How many branches go to infinity?

# HW #8 p.2

#1 (cont)

$$g_1(s) = 1/s(s + 1)(s + 4)$$

$$g_2(s) = 1/(s + 1)(s + 2 - j)(s + 2 + j)$$

$$g_3(s) = (s + 2)/(s + 1)(s + 3 - j)(s + 3 + j)$$

$$g_4(s) = 1/s(s + 1)(s + 3)(s + 4)$$

#2. (20 pts.) Use MatLab to draw each of the root-locus plots in #1.

3. Take the first two digits of your SSN, multiply them and set  $c = \text{last digit} + 2$ .

3(a). Compute the steady-state response of the system with transfer function  $g(s) = (s-1)/(s+1)$  for the driving signal  $R(t) = \sin(ct)$  (10pts.)

3(b). Using MATLAB draw the Bode plot of  $g(s)$ . (When did this the logs of the magnitudes were too small to get a good plot. So I scaled the problem by getting the Bode plots of  $100 g(s)$ . If you do something like this, be sure to explain what these Bode plots means for the Bode plot of  $g(s)$ . Hint: one of them is unchanged.) (5pts.)

3(c). Interpret your answer to 3(a) using the Bode magnitude and phase plots in 3(b). (5pts.)

3(d) Design a 1<sup>st</sup> order stable cascade controller  $k(s)$  so that the steady state response of the feedforward system  $g(s)k(s)$  to the input  $R = \sin(ct)$  is  $\sin(ct)$

(10 pts.)

(Hint: Design a stable  $k(s) = K(s+a)/(s+b)$  so that  $|k(jc)| = 1/|g(jc)|$  and so that

$$\angle k(jc) = - \angle g(jc)$$

4. Problem 6.14 in the text book on page 200,  
part (a) (10 points),  
part (c) (5 points)